



Kannavari Sangham (R)-1952

K.S.GROUP OF INSTITUTIONS

K.S. INSTITUTE OF TECHNOLOGY

(Approved by AICTE & Affiliated to VTU)

KANAKAPURA ROAD, BANGALORE - 560109

A.P.J. ABDUL KALAM

"Tell me and I'll forget;
Show me and I may
remember; Involve me
and I'll understand"

GRAHAM BELL

MARIE CURIE

SRINIVASA
RAMANUJAN

J.R.D. TATA

THOMAS ALVA EDISON

DENNIS RITCHIE

PRACTICAL RECORD

NAME : SREEKAR K.B

SEM/ BRANCH: 7th SEM MECHANICAL

SUBJECT & CODE: CIM LAB

USN :

1	K	S	I	6	M	E	O	8	5
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K.S. INSTITUTE OF TECHNOLOGY

VISION

"To impart quality technical education with ethical values, employable skills and research to achieve excellence"

MISSION

- * To attract and retain highly qualified, experienced & committed faculty.
- * To create relevant infrastructure
- * Network with industry & premier institutions to encourage emergence of new ideas by providing research & development facilities to strive for academic excellence
- * To inculcate the professional & ethical values among young students with employable skills & knowledge acquired to transform the society



K.S.INSTITUTE OF TECHNOLOGY, BANGALORE
#14, Raghuvanahalli, Kanakapura Main Road, Bengaluru-560109
DEPARTMENT OF MECHANICAL ENGINEERING

Vision of the Department

"To groom incumbents to compete with their professional peers in mechanical engineering that brings recognition"

Mission of the Department

- To impart sound fundamentals in mechanical engineering
- To expose students to new frontiers
- To achieve engineering excellence through experiential learning and team work.

PROGRAM EDUCATIONAL OBJECTIVES (PEO's)

- **PEO1:** To produce graduates who would have developed a strong background in basic science and mathematics and ability to use these tools in Mechanical Engineering.
- **PEO2:** To prepare graduates who have the ability to demonstrate technical competence in their fields of Mechanical Engineering and develop solutions to the problems.
- **PEO3:** To equip graduates to function effectively in a multi-disciplinary environment individually, within a global, societal, and environmental context.

PROGRAM SPECIFIC OUTCOMES (PSO's)

- It is expected that a student in mechanical engineering will possess an:
- **PSO1:** Ability to apply concept of mechanical engineering to design a system, a component or a process/system to address a real world challenges
- **PSO2:** Ability to develop effective communication, team work, entrepreneurial and computational skills

COURSE LEARNING OUTCOMES:

After completing the course, students will be able to		
15MEL77.1	Explain the concepts of Computer Integrated manufacturing and Classify NC, CNC and DNC systems.	Understanding (K2)
15MEL77.2	Develop manual part programs to perform milling, drilling and turning operations in design, simulation and manufacturing.	Applying (K3)
15MEL77.3	Analyze the Simulation of Tool Path for different Machining operations of small components using CNC Lathe & CNC Milling Machine.	Analyzing (K4)
15MEL77.4	Identify the concepts of flexible manufacturing systems like Automatic storage and Retrieval system and utilize Robot programming language for simple operations such as pick and place, stacking objects using teach pendent and off line programming.	Applying (K3)
15MEL77.5	Apply the knowledge of pneumatics and hydraulics to demonstrate the related experiments	Applying (K3)



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KANAKAPURA ROAD, BANGALORE - 560 062

Laboratory Certificate

This is to certify that Mr./Ms.SREEKARA, K.B.....
has satisfactorily completed the course of experiments in
.....C.I.M.....laboratory, Code..15MEL77
prescribed by Visvesvaraya Technological University, Belgaum for
the.....7.....Semester B.E.....MECHANICAL.....Branch
in this College during the academic year 20.19... - 20.20..

Name of the Candidate : SREEKARA, K.B.....

USN : 1KS16ME085.....Subject (with code) C.I.M. LAB. 15MEL77

Internal assessment marks awarded :

10	10	20
10	10	20

Signature of Staff Incharge

Date: 26/11/19 -

Signature of Head of
Head of the Department
Dept. of Mechanical Engg.
K.S. Institute of Technology
Bengaluru - 560 109.

INSTRUCTIONS FOR MAINTAINING THE PRACTICAL RECORD

1. Record should be written neatly in ink on the right side page only, left side pages being reserved for diagrams and graphs in pencil.
2. Record should contain
 - Number and name of the Experiment
 - The date
 - Principle
 - Procedure
 - Observation calculation (to be entered on the left hand side pages in neat tabular forms wherever applicable)
 - Results

CONTENTS AND EVALUATION

Sl.No.	Date of Conducting Experiment	Date of Submission	Page No.	Title of the Experiment	Assessment Marks			Signature of Staff with Date
					Experiment 10 Marks	Record 5 Marks	Total	
1	22/08/19	29/08/19	1-8	Introduction	10	20	30	[Signature]
2	29/08/19	12/09/19	9-10	Simple facing	10	20	30	
3	29/08/19	12/09/19	11-12	Simple facing cycle	10	19	29	
4	29/08/19	12/09/19	13-14	Simple turning	10	19	29	[Signature]
5	29/08/19	12/09/19	15	Simple turning cycle	10	20	30	
6	12/09/19	19/09/19	16	Step turning	10	20	30	
7	12/09/19	19/09/19	17-19	Taper turning	10	20	30	[Signature]
8	19/09/19	26/09/19	20*	Countouring	10	20	30	
9	19/09/19	26/09/19	21	Multiple turning	10	20	30	
10	26/09/19	03/10/19	22-23	External grooving	10	20	30	[Signature]
11	03/10/19	10/10/19	24-25	Subprogram	10	20	30	
12	10/10/19	17/10/19	26-27 25-26	Multiple threading	10	20	30	

CONTENTS AND EVALUATION

Sl.No.	Date of Conducting Experiment	Date of Submission	Page No.	Title of the Experiment	Assessment Marks			Signature of Staff with Date
					Experiment 10 Marks	Record 5 Marks	Total	
13	17/10/19	24/10/19	28	Peck Drilling	10	19	29	Hand
14	17/10/19	24/10/19	29-30 29-30	Step Boring	10	20	30	
15	17/10/19	24/10/19	31-32 30-31	Internal Multiple Turning	10	20	30	Hand
16	24/10/19	31/10/19	33-34	Internal Threading	10	20	30	
17	21/10/19	14/11/19	35-37	Introduction to milling	10	20	30	Hand
18	14/11/19	27/11/19	38-39	Linear interpolation	10	20	30	
19	14/11/19	27/11/19	40	Circular interpolation	10	20	30	Hand
20	14/11/19	27/11/19	41-42	Linear & circular interpolation	10	20	30	
21	14/11/19	27/11/19	43-44	minimizing	10	19	29	Hand
								Avg
								Avg
								Total

Numerical Control (NC):

It can be defined as form of programmable automation in which the process is controlled by numbers, letters and symbols in NC the numbers forms a program of instructions designed for a particular work part or job.

When the job changes the program of instruction is changed. This capability will change program for each new job is what gives NC flexibility.

Ex: G00 X0 Y0 Z0

Computer numerical control (CNC):

Numerical control integrated computer control includes one or more microprocessor, minicomputers. The logic function or program the control comprises a program that is stored in the memory.

Direct Numerical control (DNC):

It can be defined as a manufacturing system in which a number of machines are controlled by a computer through direct connection and in real time.

NC motion control system:

In NC there are 3 basic types of machine control system

- i) Point to point
- ii) Straight cut
- iii) Contouring.

i) Point to Point:

It is also sometimes called positioning system. In point to point the objective of the machine tool control system is to the cutting to predefined location once

the tool reaches the defined location the machining operation is performed at that position.

Ex: NC drill presses.

ii) Straight cut NC:

Straight cut control system is capable of moving the cutting tool, parallel to one of the major axes at controlled rate suitable for machining. It is therefore appropriate for performing milling operation to fabricate work piece of rectangular configurations.

Post programming fundamentals :

The following are the basic steps in NC procedure

Process planning

Part programming

Part programming entry

Proving the part

Program production

Process planning :

The part programmer will often carry out the tasks of process planning. Process planning is the procedure of deciding what operations are to be done on the component, in what order, and with what tooling work holding facilities. Both the process planning and part programming aspects of manufacture occur after the detail drawings of a component have been prepared. The following procedure may be used as a guide to assist the programmer, by describing each step required in preparing the method of production.

- Receive the part drawing, from part drawing information, check suitability of the part to be machined against the machine capacity.
- Determine a method of driving the component (chuck type, chuck size, type of jaw) and the method of machining.
- Determine the tooling required to suit the method of machining and utilize as much as possible the tools which are permanently in the turret set upon the machine.
- Determine the order of machining and the tooling stations.
- Determine the planned stops for checking dimensional sizes required by operation.
- Determine cutting speeds based on
- Component material, method of driving, rigidity of component tooling selected for roughing & finishing.
- Determine the depth of cut and feeds for roughing operations.
- Determine surface finish requirements, the cutter nose radius most suited for finishing operations and determine feed rates. Allocates tool offsets as required complete planning sheet.

Part programming:

After completing the planning sheet, draw the component showing the cutter paths (a simple sketch is sufficient for simple components)

- Select a component datum and carryout the necessary calculations at slopes and arcs
- Prepare tooling layout sheet showing tools to be used in the program and indicate the station numbers for each tool
- Indicate the ordering code for each tool grade and type of inserts to be used.
- Write the part program according to the sequence of operations.

Part program entry on tape preparation:

The part program is prepared/punched on a 25mm wide paper tape with 8 tracks and is fed to MCU in order to produce a component of interest on machine tool. Other forms of input media include punched cards, magnetic tape, 35mm motion picture film. The input to the NC system can be in two ways

➤ Manual data input (MDI): Complete part programs are entered into CNC control unit via the console keyboard. It is suited only for relatively simple jobs. The most common application for MDI is the editing of part programs already resident in controller's memory.

One variation of MDI is a concept called Conversational Programming. CNC machines are programmed via a question and answer technique whereby a resident software program asks the operator a series of questions. In response to the operator's input, and accessing a pre-programmed data file, the computer control can

- Select numerical values for use within machining calculations
- Perform calculations to optimize machining conditions
- Identify standard tools and co-ordinates
- Calculate cutter paths and co-ordinates
- Generate the part program to machine the component.

A typical dialogue from the machine would be as follows for the operator to identify such things as

- Material to be cut
- Surface roughness tolerances
- Machined shape required
- Size of the raw material blank
- Machining allowances, cut directions, tools & tool detail etc.

The operator may then examine and prove the program via computer graphics simulation on the console VDU. After this, the program is stored or punched on tape. Although there is some sacrifice in machine utilization, actual programming time is minimal and much tedious production engineering work is eliminated.

2) Direct Numerical control: The process of transferring part programs into memory of a CNC machine tool from a host computer is called Direct numerical control or DNC.

Providing part programs:

It is safe practice to check the programmed path for any interference between the tool and the work before using the part program for production. The proving part program is done by

- Visual inspection
- Single step execution dry run

Visual inspection: It represents the method of checking visually the program present in the memory of the CNC machine. In this, actual program is run and the programmed movements in all axes are to be checked along with ensuring the tool offset and cutter compensation feature. This method represents the least form of verification and should not be relied upon entirely.

Single step execution: Before auto-running the part program it should be executing in a step mode i.e. block by block. During this execution, speed and feed rate override facilities are to be used so that axes movement

M Codes

M00	Program stop
M02	Optional stop
M03	Spindle forward
M04	Spindle reverse
M05	Spindle stop
M06	Tool change
M08	Coolant on
M09	Coolant off
M10	Vice open
M11	Vice close
M13	Spindle forward, coolant on
M14	Spindle reverse, coolant on
M30	Program end
M38	Door open
M39	Door close
M98	Subprogram call
M99	Subprogram exit

can be exactly monitored. This operation may be carried out with or without mounting the component on the machine.

Part Programming Geometry :

Coordinate system for a CNC lathe :

Machining of a workpiece by an NC program requires a coordinate system to be applied to the machine tool. As all machine tools have more than one slide, it is important that each slide is identified individually. There are two planes in which movements can take place.

Longitudinal

Transverse

Each plane is assigned a letter and is referred to as an axis

Axis X

Axis Z

The two axes are identified by upper case X, Z and the direction of movement along each axis + or - The Z axis is always parallel to the main spindle of the machine. The X axis is always parallel to the work holding surface, and always at right angles to the Z axis. The coordinate system for turning operation is shown in fig. below.

Zero points and Reference points

All CNC machine tool traverses are controlled by coordinating systems. Their accurate position within the machine tool is established by zero points.

Machine zero point (M): is specified by the manufacturer of the machine. This is the zero point for the coordinate systems and reference points.

G codes

G00	Positioning
G01	Linear interpolation
G02	Circular interpolation (CW)
G03	Circular interpolation (CCW)
G04	Dwell
G20	Inch data input
G21	Metric data input
G28	Reference point return
G40	Tool nose radius compensation cancel
G41	Tool nose radius compensation left
G42	Tool nose radius compensation right
G50	Works coordinate change
G70	Finishing cycle
G71	Multiple turning cycle
G72	Stock removal in facing
G73	Pattern repeating
G74	Peck drilling in Z axis
G75	Grooving in X axis
G76	Thread cutting cycle
G90	Cutting cycle A (Turning)
G94	Cutting cycle B (Facing)
G96	Constant surface speed control
G97	Constant surface speed control cancel
G98	Feed per revolution
G99	Feed per minute.

in the machine. On turning lathes, the machine zero point is generally at the center of the spindle nose face. The main spindle axis (centre line) represents the Z axis, the face determines the X axis. The directions of the positive X and Z axes point toward the working area as shown in figure below.

Workpiece zero point (W): This point determines the workpiece coordinate system in relation to the machine zero point. The workpiece zero point is chosen by the programmer and input into the CNC system when setting up the machine. The position of the workpiece zero point can be freely chosen by the programmer within the work piece envelope of the machine. It is however advisable to place the workpiece zero point in such a manner that the dimensions in the workpiece drawing can be conveniently converted into coordinate values and orientation when clamping / chucking, setting up and checking, the transverse measuring system can be effected easily.

For turned parts, the workpiece zero point should be placed along the spindle axis (centre line), in line with the right hand or left hand end face of the finished contour as shown in fig.

Occasionally the workpiece zero point is also called the program zero point

Reference point (R): This point serves for the calibrating and for controlling ~~the~~ ^{the} measuring system of the slides and tool traverses. The position of the reference point as shown in fig. below is accurately predetermined in every transverse axis by the trip dogs and limit switches. Therefore, the reference point coordinates always have the same, precisely known numerical value in relation to the machine zero point. After

	Vingko Aitana
Record	20
Observation	5
Visit	5
Total	30
Signature of Faculty with date	A. A. J.

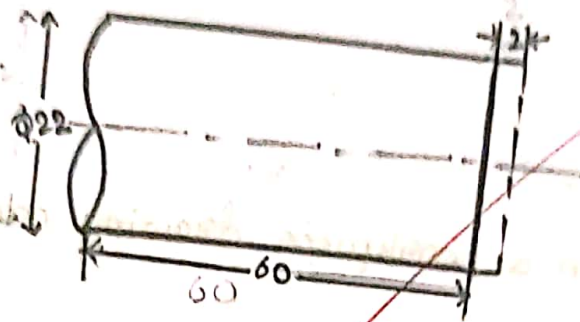
initiating the control system, the reference point must always be approached from all axes to calibrate the traverse measuring system. If current slide and tool position data should be lost in the control system as for example, through an electrical failure, the machine must again be positioned to the reference point to re-establish the proper positioning values.

CNC-related dimensioning:

Dimensional information in a workpiece drawing can be stated in two ways:

1) Absolute Dimension system: Data in absolute dimension system always refer to a fixed reference point in the drawing as shown in figure. A above. This point has the function of a coordinate zero point as in figure B. The dimension lines run parallel to the coordinate axes and always start at the reference point. Absolute dimensions are also called as 'Reference dimensions'.

2) Incremental Dimension system: When using incremental dimension system, every measurement refers to a previously dimensioned position as shown in figure A below. Incremental dimensions are distance between adjacent points. These distances are converted into incremental coordinates by accepting the last dimension point as the coordinate origin for the new point. This may be compared to a small coordinate system i.e. shifted consequently from point to point as shown in figure B. Incremental dimensions are also frequently called 'Relative dimensions' or 'Chain dimensions'.



Planning and operations sheet

Billet size: 22 X 60				Material: Aluminium			
Program No: 1001				DWG No: 1			
Sl. no.	Operation	Tool Holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
	Simple facing	SDJCR1212H11	DCMT11T300	1	1	1200	45

DATE ... 29/08/19
EXP. NO. ... 2

EXPT. TITLE : SIMPLE FACING

PAGE NO.

9

Write a manual part program for simple facing operation for the component shown in figure below.

~~O1001~~

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X22 Z1

F45

G01 X0

G01 Z0

G01 Z1

G00 X22

G01 Z-0.5

G01 X0

G01 Z1

G00 X22

G01 Z-1

G01 X0

G01 Z1

G00 X22

G01 Z-1.5

G01 X0

G01 Z1

G00 X22

G01 Z-2

DATE

EXPT. TITLE :

EXP. NO.

PAGE NO.

10

G01 X0

G01 Z1

G00 X22

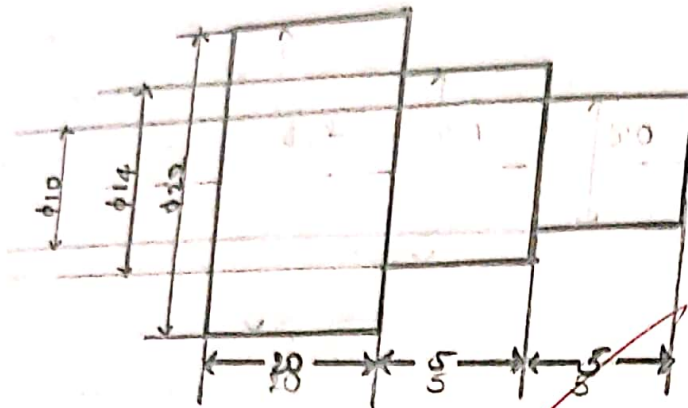
G28 00 W0

M05

M30

19
20

	Marks Allotted
Record	19
Observation	5
Viva	5
Total	29
Signature of Faculty with date	<i>nd</i>



Planning and operations sheet:

Billet size: 22 x 30				Material: Aluminium			
Program No: 1004				DWG No: 2			
Sl. no.	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
1	Facing	SDICR1212H11	DCMT11T304	1	1	1200	45

DATE 29/08/19
EXP. NO. 3

EXPT. TITLE : SIMPLE FACING CYCLE

PAGE NO.

11

Write a manual part program for facing operation for the component shown in figure below

G121 G98

G128 U0 W0

M06 T0101

M03 S1200

G00 X22 Z1

F35

G01 Z0

G94 X10 Z-0.5

Z-1

Z-1.5

Z-2

Z-2.5

Z-3

Z-3.5

Z-4

Z-5

G00 X22 Z-5

G94 X14 Z-5.5

Z-6

Z-6.5

Z-7

Z-7.5

Z-8

Z-8.5

2-9

2-9-9

2-10

0000 00 000

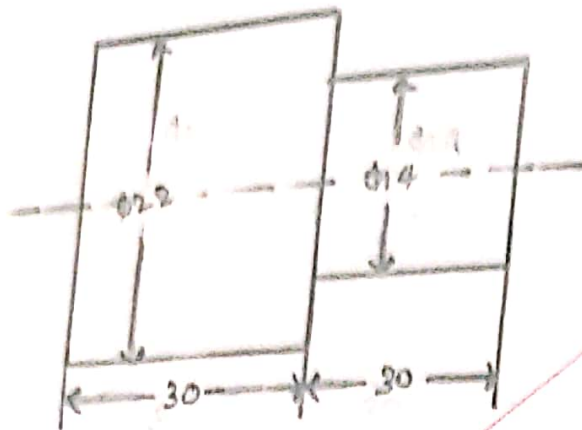
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	Marks Allotted
Record	19
Observation	5
Viva	5
Total	29
Signature of Faculty with date	nd



Planning & operations sheet

Billet size: 22 X 60				Material: Aluminium			
Program No: 1002				DWG No: 3			
Sl. no.	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
1	Simple turning	SDJCR1212H11	DCMT11T304	1	1	1200	45

DATE ... 29/08/2019 ...
EXP. NO. ... 4 ...

EXPT. TITLE : Simple Turning

PAGE NO. 13

Write a manual part program for simple turning operation for the component shown in the figure below.

```
G21 G98  
G28 U0 W0  
M06 T0101  
M03 S1200  
G00 X22 Z1  
F45  
G01 X21  
G01 Z-30  
G00 X22  
G00 Z1  
G01 X20  
G01 Z-30 F  
G00 X22  
G00 Z1  
G01 X19  
G01 Z-30  
G00 X22  
G00 Z1  
G01 X18  
G01 Z-30  
G00 X22  
G00 Z1  
G01 X17  
G01 Z-30
```


600 822

600 81

600 814

600 8-80

600 822

600 81

600 815

600 8-80

600 822

600 81

600 814

600 8-80

600 822

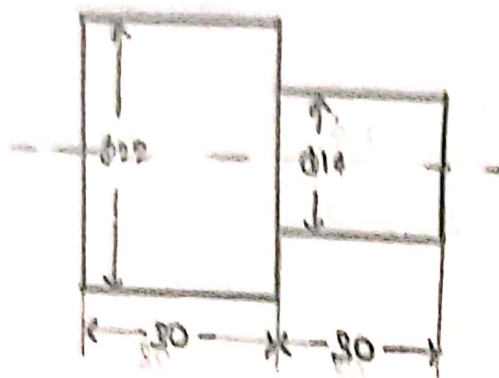
600 81

600 80 80

600

600

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	nd



Planning and operation sheet

Billet size: 22 x 60				Material: Aluminium			
Program No.: 1002				DWG No.: 4			
Sl. no	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
1	Simple turning	SOLAR 1212111	DCMT11T304	1	1	1200	15

DATE 29/08/19
EXP. NO. 5

EXPT. TITLE: SIMPLE TURNING CYCLE

PAGE NO. 15

Write a manual part program for simple turning operation for the component shown in figure below.

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X22 Z1

F45

G01 Z0

G90 X21 Z-30

X20

X19

X18

X17

X16

X15

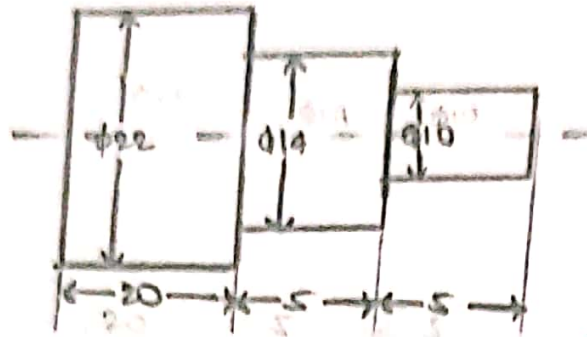
X14

G28 U0 W0

M05

M30

	Marks Allotted
Record	19
Observation	5
Viva	5
Total	29
Signature of Faculty with date	<i>[Signature]</i>



Planning & operation sheet

Billet size: 22x30				Material: Aluminium			
Program No: 1007				DWG No: 5			
Sl. no.	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed
1	step turning	SARCR 1212H11	PLMT 11T304	1	1	1200	30

DATE 12/09/19
EXP. NO. 6

EXPT. TITLE : STEP TURNING

PAGE NO. 16

Write a manual part program for step turning operation with G90 cycle for the component shown in figure below.

G21 G98

G28 W0 W0

M06 T0101

M03 S1200

G00 X22 Z1

G01 F30

G01 Z0

G90 X21 Z-10

X20

X19

X18

X17

X16

X15

X14

G00 X14 Z1

G90 X13 Z-5

X12

X11

X10

G28 W0 W0

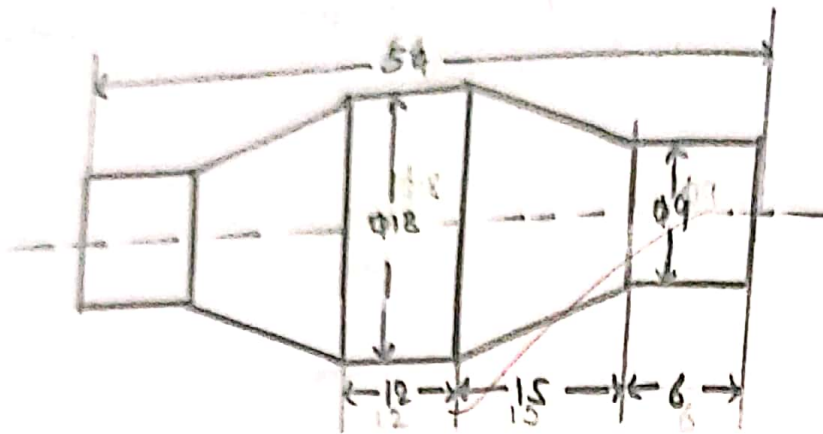
M05

M30

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	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	

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Planning & operations sheet

Billet size : 22 x 54				Material : Aluminium			
Program No : 1008				DWG No : 9			
Sl. no.	Operations	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed
1	Taper turning	SATCR 1212 H11	DCMT11T304	1	1	1200	35

DATE 12/09/19

EXPT. TITLE

TAPER TURNING CYCLE

EXP NO

7

PAGE NO.

17

Write a manual part program for taper turning operation for the component shown in figure below.

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X22 Z1

G01 Z0 F35

G90 X21 Z-54

X20

X19

X18

X17 Z-6

X16

X15

X14

X13

X12

X11

X10

X9

G00 X18 Z-6

G90 X18 Z-21 R0

X18 R-0.5

X18 R-1

X18 R-1.5

X18 R-2

X18 R-2.5

X18 R-3

X18 R-3.5

X18 R-4

X18 R-4.5

G01 X18 2-33

G90 X18 2-48 R0

X17 R0.5

X16 R1

X15 R1.5

X14 R2

X13 R2.5

X12 R3

X11 R3.5

X10 R4

X9 R4.5

G00 X18 2-48

G90 X18 2-54

X17

X16

X15

X14

X13

X12

X11

X10

DATE

EXPT. TITLE :

EXP. NO.

PAGE NO.

19

x9

G28 VO WO -

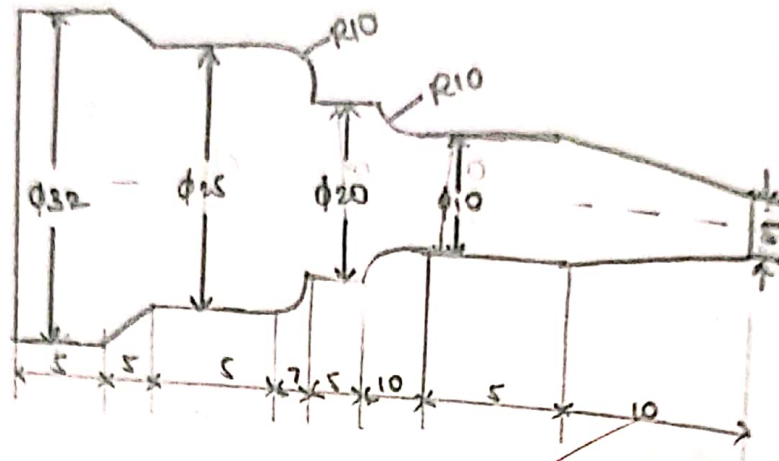
M05

M30

20
20

N. S. S.

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	<i>md</i>



Planning & operations sheet

Billet size: 32x52				Material: Aluminium			
Program no.: 1003				DWG No: 8			
Sl. no	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed
1	Turning	SDJCR 1212H11	DMT 11 T304	1	1	1200	0.1

DATE 19/09/19
EXP. NO. 3

EXPT. TITLE: CONTOURING

PAGE NO. 80

Write a manual part program for Linear and circular contour operation for the component shown in fig. below

O1003

BILLET X32 Z52

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X32 Z1

G01 Z0 F30

G00 X5

G01 X10 Z-10 F45

G01 X10 Z-15

G02 X20 Z-25 R10 F25

G01 Z-30 F45

G03 X25 Z-37 R10 F25

G01 Z-42 F45

G01 X32 Z-47

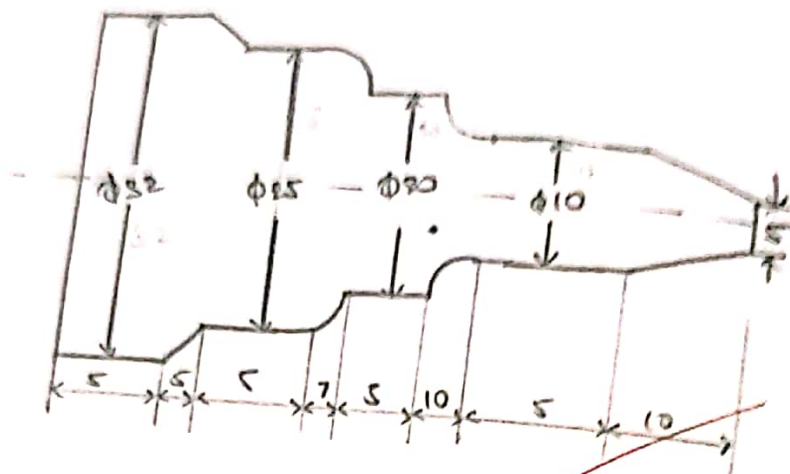
G01 Z-52

G28 U0 W0

M05

M30

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	md



Planning & operations sheet

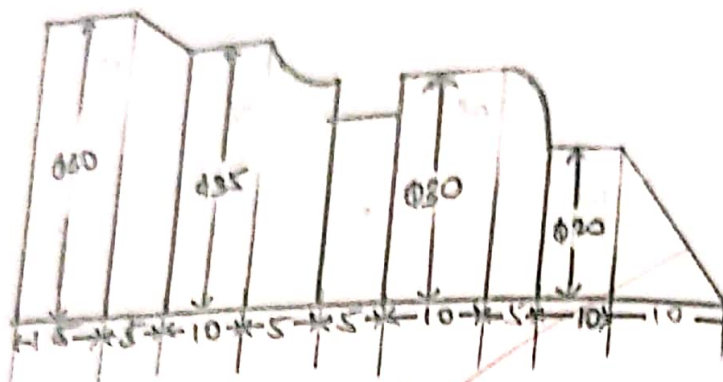
Billet size: 32x52				Material: Aluminium			
Program no. 1009				DWG No. 1009			
Sl no	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed
1	Rough turning	SDJCR 1212H11	DcmT 11T304	1	1	1200	0.5
2	Finishing	SDJCR 1212H11	DcmT 11T302	2	2	1200	0.5

Write a manual part program for multiple turning operation for the component shown in figure below

G01 G98
G28 U0 W0
M06 T0101
M03 S1200
G00 X32 Z1
G71 U0.5 R1
G71 P10 Q20 U0.1 W0.1 F25
N10 G01 X5
G01 Z0
G01 X10 Z-10
G01 Z-15
G02 X20 Z-25 R10
G01 Z-30
G03 X25 Z-37 R10
G01 Z-48
G01 X30 Z-47
N20 G01 Z-52
G28 U0 W0
M06 T0202
M03 S1450
G00 X32 Z1
G70 P10 Q20 U0 W0 S2500 F30
G28 U0 W0

20 M05 M30

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	md



Planning & operations sheet

Billet size: 40x75				Material: Aluminium			
Program no 1012				DWG no: 12			
Sl no	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed
1	Rough turning	SDTCR 1212H11	DCMT 11T304	1	1	1200	45
2	Finishing	SDTCR 1212H11	DCMT 11T3042	2	2	1450	25
3	Grooving	HSS	3mm width	5	5	750	15

Write a manual part program for external grooving operation for the component shown in figure below.

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X40 Z1

G01 Z0 F35

G71 U0.5 R1

G71 P20 Q40 U0.1 W0.1 F30

N20 G01 X0

G01 X20 Z-10

G01 X20 Z-20

G03 X30 Z-25 R5

G01 Z-40

G02 X35 Z-45 R5

G01 X35 Z-55

G01 X40 Z-60

N40 G00 X40 Z1

G28 U0 W0

G70 P20 Q40 U0 W0 S1200 F30

G28 U0 W0

M06 T0202

M03 S2000

G00 X32 Z-37

G01 X30

G

DATE

EXP. NO

EXPT. TITLE :

PAGE NO.

23

G75 R1

G75 X20 Z40 P500 Q1000 F20

G28 U0 W0

M05

M30

20
20
40

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	<i>[Signature]</i>



Planning & operations sheet:

Billet size: 20x60				Material: Aluminium			
Program no.: 1009				DWG No: 7			
Sl no.	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
1	Taper turning	SDJCR 1212H11	DCMT 11T304	1	1	1200	35

DATE .. 03/10/19 ..
EXP. NO .. 11 ..

EXPT. TITLE : Subprogram 1

PAGE NO. 4/4

Write a manual part program by using subprograms for the workpiece shown in figure below

G21 G98

G128 U0 W0

M06 T0101

M03 S1200

G00 X20 Z1

G01 Z0 F35

M98 P0037777

G28 U0 W0

M05

M30

O7777

G90 X20 W-8 R-0.5 F50

X20 R-1

X20 R-1.5

X20 R-2

X20 R-2.5

G00 X20 W-8

G90 X19 W-8 R0.5

X18 R1

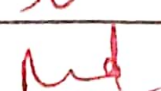
X17 R1.5

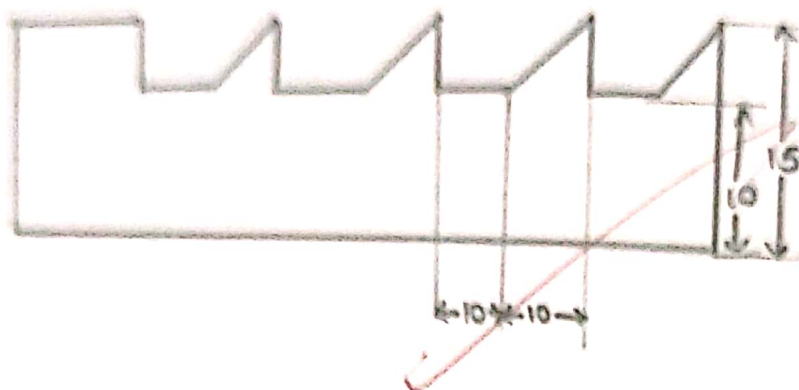
X16 R2

X15 R2.5

G00 X20 W-8

M99

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	



Billet size: 15 x 70				Material: Aluminum			
Program no.: 1009				DWR No. 8			
Sl no	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
1	Taper turning	SDSCR 1212H11	PCMT 11T304	1	1	1200	35

DATE 03/10/19
PAGE NO. 10

EXPT. TITLE: Subprogram A

PAGE NO. 25

Write a manual sort program by using subprograms for the component chain in figure below

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X15 Z1

G01 Z0

M98 P0038888

G28 U0 W0

M05

M30

O8888

G90 X14 W40 R0.5 F50

X13 R1

X12 R1.5

X11 R2

X10 R2.5

G00 X15 W10

G90 X14 W40

X13

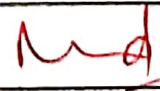
X12

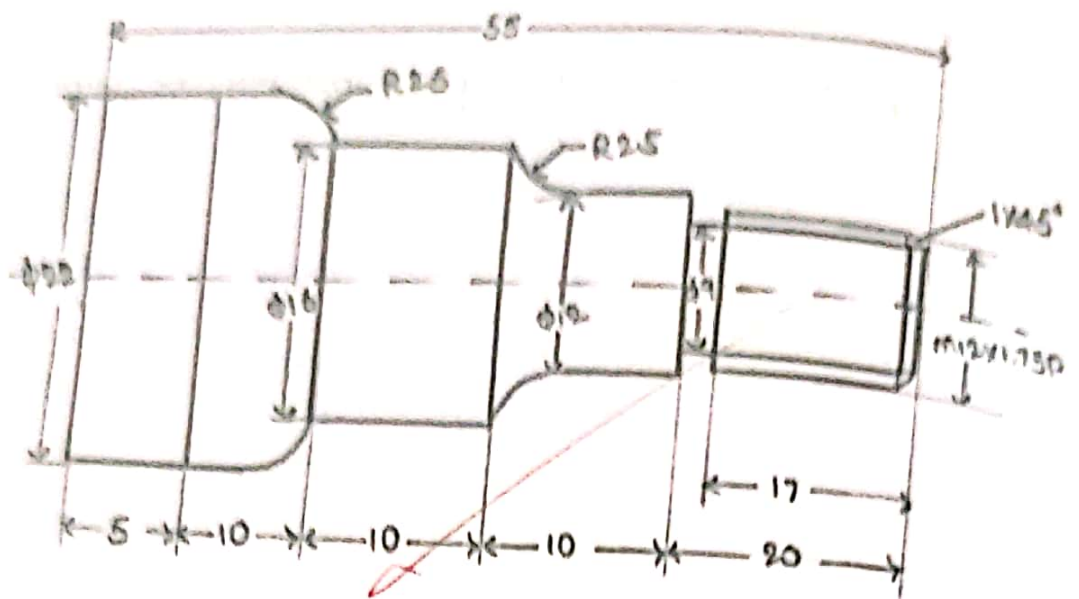
X11

X10

G00 X15 W10

M99

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	



Billet size: 22x55				Material: Aluminium			
Program no.: 1011				DWG No. 11			
Sl. no.	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle Speed	Feed mm/min
1	Multiple rough turning	SDSCR 1212H11	DCMT 11T304	1	1	1200	35
2	Finishing	SDSCR 1212H11	DCMT 11T302	2	2	1050	25
3	Grooving	HSS	3 mm width	5	5	750	25
4	Threading	HSS		7	7	500	25

Write a manual part program for external threading operation for the component

G121 G198

G128 U0 W0

M06 T0101

M03 S1200

G00 X22 Z1

G01 Z0

G71 U0.5 R1

G71 R10 Q20 U0.1 W0.1 F25

N10 G01 X10

G01 Z0

X12 Z-1

Z-20

G02 X16 Z-30 R25

G01 Z-40

G03 X22 Z-50 R25

N20 G01 Z-55

G28 U0 W0

M06 T0202

M03 S1450

G00 X22 Z1

G70 P10 Q20 F25

G28 U0 W0

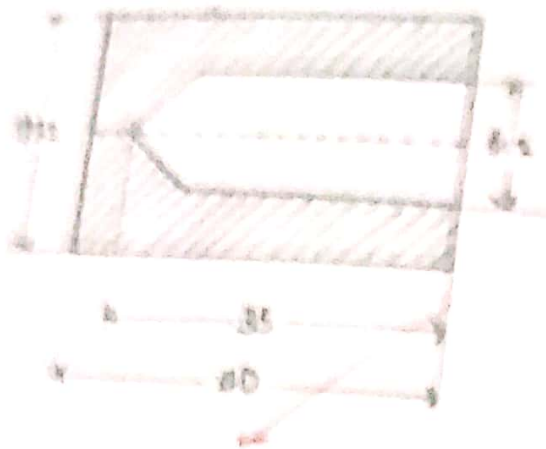
M06 T0505

M03 S650

Q101 K15 2-19
 Q102 81
 Q103 K1 2-20 F.25
 Q104 100 100
 Q105 10000?
 Q106 K12 20
 Q107 1000000 0.10 10.15
 Q108 K1 K5.5 2-15 10013 0.30 F.1.75
 Q109 100 100
 Q110
 Q111

100
 100
 100

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	10/1



Planning & operations sheet

Billet size 32x20

Program No : 1015

Material : Aluminium

DWG No 15

Sl no	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
1	Center drill	6mm	-	6	6	1200	20
2	Drilling	12mm	-	8	8	800	20

DATE 17/10/19
EXP. NO. 1A

EXPT. TITLE: PECK DRILLING

PAGE NO. 02

Write a manual part program for peck drilling operation for the component shown in figure below.

G21 G98

G28 U0 W0

M06 T0606

M03 S1200

G00 X0 Z2

G01 Z0 F20

G74 R1

G74 X0 Z-5 Q500 F20

G28 U0 W0

M06 T0808

M03 S800

G00 X0 Z2

G74 R1

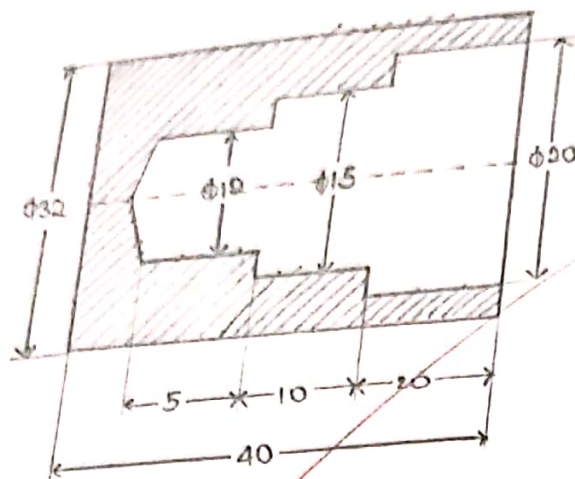
G74 X0 Z-3.5 Q500 F20

G28 U0 W0

M05

M30

	Marks Allotted
Record	19
Observation	5
Viva	5
Total	29
Signature of Faculty with date	<i>[Signature]</i>



Planning & operations sheet

Billet size: 32x40				Material: Aluminium			
Program No: 1016				DWG No: 16			
Sl. no.	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/min
1	Center drill	6mm	-	1	1	1200	20
2	Drilling	12 mm drill	-	8	8	800	15
3	Boring	100mm boring	-	2	2	1200	20

DATE 17/10/19
EXP. NO 15

EXPT. TITLE : STEP BORING

PAGE NO. 24

Write a manual part program for step boring operation for the component shown in figure below.

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X0 Z2

G01 Z0 F20

G74 R1

G74 X0 Z-5 Q500 F20

G28 U0 W0

M06 T0808

M03 S800

G00 X0 Z0

G74 R1

G74 X0 Z-3.5 Q500 F15

G28 U0 W0

M06 T0202

M03 S1200

G00 X12 Z1

G01 Z0

G90 X13 Z-30 F20

X14

X15

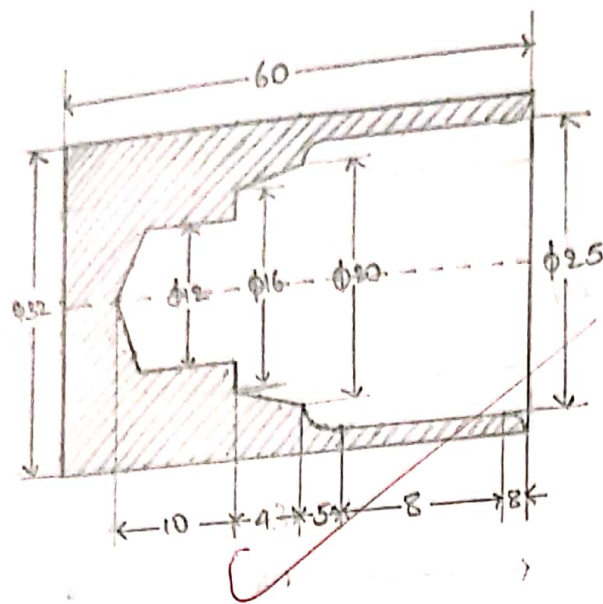
X16 Z-20

X17

X18
X19
X20
G28 UD W0
M05
M30

90
78
md

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	<i>md</i>



Planning & operations sheet

Billet size : 32 x 40				Material : Aluminium			
Program No. : 1017				DWG No. : 17			
Sl. no.	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed mm/r
1	Center drill	6mm	-	1	1	1200	15
2	Drilling	12mm drill	-	2	2	700	15
3	Boring	10mm	-	3	3	800	20

DATE 17/10/19
EXPT. NO. 16

EXPT. TITLE INTERNAL MULTIPLE TURNING

PAGE NO. 31

Write a manual part program for internal multiple turning operation for the component shown in figure below

G21 G98

G28 U0 W0

M06 T0101

M03 S1200

G00 X0 Z2

G01 Z0

G74 R1

G74 X0 Z-5 Q500 F15

G28 U0 W0

M06 T0202

M03 S1000

G00 X0 Z1

G01 Z0

G74 R1

G74 X0 Z-35 Q500 F15

G28 U0 W0

M06 T0303

M03 S800

G00 X12 Z1

G01 Z0

G71 U0.2 R1

G71 P10 Q20 U0.1 W0.1 F20

N10 G01 X20

G02 X25 Z-8 R8 F15

G01 2-16 F20

G03 X20 2-21 R3 F15

G01 X16 2-31 F20

N20 G01 X12

G70 P10 Q20 U0 W0 S1000 F20

G28 U0 W0

M25

M30

(Handwritten signature/initials)

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	<i>(Handwritten signature)</i>



Planning & operations sheet

Billet size : 25 x 70				Material: Aluminium			
Program no : 1011				DWG No. 11			
Sl no	Operation	Tool holder	Tool tip	Tool station	Tool offset	Spindle speed	Feed rate
1	Center drill	6mm	✓	1	1	800	20
2	Drilling	12 mm drill	-	2	2	1200	15
3	Boring	10 mm boring bar	-	3	3	800	20
4	Threading	HSS	-	4	4	1000	15

Write a manual part program for internal threading operation for the component shown in figure below.

G21 G98

G28 U0 W0

M06 T0101

M03 S800

G00 X0 Z1

G01 Z0

G74 R1

G74 X0 Z-5 Q500 F50

M06 T0202

M03 S1200

G00 X0 Z1

G01 Z0

G74 R1

G74 X0 Z-30 Q500 F50

G00 X0 Z1

G28 U0 W0

M06 T0303

M03 S800

G00 X12 Z1

G01 Z0

G90 X13 Z-20

X14

X15

X16

X17

X18

X18.774

G128 UO W0

M06 T0404

M03 S1000

G100 X16 Z1

G101 Z0

G176 P031560 Q50 R0.1

G176 X10 Z-20 P0613 Q100 F1

G128 UO W0

M05

M30

20
20
20

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	<i>[Signature]</i>

M CODES :

M00	Program stop
M01	Optional stop
M02	Program end
M03	Spindle forward
M04	Spindle reverse
M05	Spindle stop
M06	Tool change
M08	Coolant on
M09	Coolant off
M10	Vice open
M11	Vice close
M13	Coolant, spindle forward
M14	Coolant, spindle reverse
M30	Program stop and rewind
M70	X mirror on
M71	Y mirror on
M80	X mirror off
M81	Y mirror off
M98	Subprogram call
M99	Subprogram exit

G1 CODES :

G00	Positioning (Rapid transverse)
G01	Linear interpolation (Feed)
G02	Circular interpolation (cw)
G03	Circular interpolation (ccw)
G04	Dwell
G20	Inch data input
G21	Metric data input
G28	Reference point return
G40	Tool nose radius compensation cancel
G41	Tool nose radius compensation left
G42	Tool nose radius compensation right
G43	Tool length compensation + direction
G44	Tool length compensation - direction
G73	Peck drilling cycle
G74	Counter tapping cycle
G76	Fine boring
G80	Canned cycle cancel
G81	Drilling cycle, spot boring
G82	Drilling cycle, counter boring
G83	Peck drilling cycle
G84	Tapping cycle
G85	Boring cycle
G86	Boring cycle
G87	Back boring cycle
G88	Boring cycle
G89	Boring cycle

G90	Absolute command
G91	Incremental command
G92	Programming of absolute zero point
G94	Feed per minute
G95	Feed per revolution
G98	Return to initial point in canned cycle
G99	Return to R point in canned cycle

Handwritten signature/initials

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	<i>Handwritten signature</i>

DATE
EXPT. NO. 19

Write a manual part program for linear interpolation for the component shown in figure below.

G21 G94

G91 G28 Z0

G28 X0 Y0

M06 T0101

M03 S1500

G90 G00 X30 Y30 Z5

G01 Z-1 F30

G01 X70 Y30 F60

G01 X70 Y70

G01 X30 Y70

G01 X30 Y30

G00 Z5

G91 G28 Z0

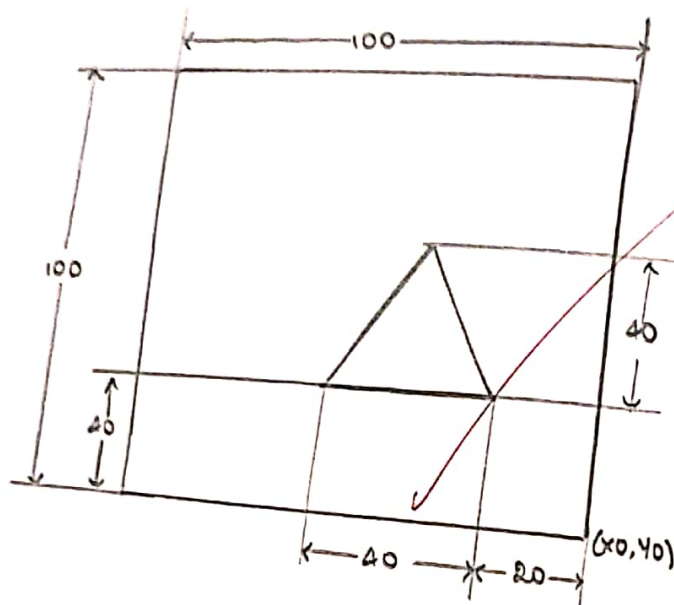
G28 X0 Y0

M05

M30

20
20
md

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	md



Planning & operation sheet:

Billet size : 100x100x10				Material : Aluminium			
Program no. : 10201				DWG No. : 21			
Sl. no.	Operation	Tool type	Tool dia	Tool station	Tool length offset	Spindle speed	Feed mm/min
1	Linear	Slot cutter	6mm	1	1	2000	30-50

Write a manual part program for linear interpolation for the component shown in figure below

G21 G94

G91 G28 Z0

G28 X0 Y0

M06 T0101

M03 S1500

G90 G100 X-20 Y40 Z5

G101 Z-1 F30

G101 X-60 Y40 F30

G101 X-40 Y80

G101 X-20 Y40

G100 Z5

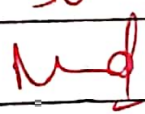
G28 Z0

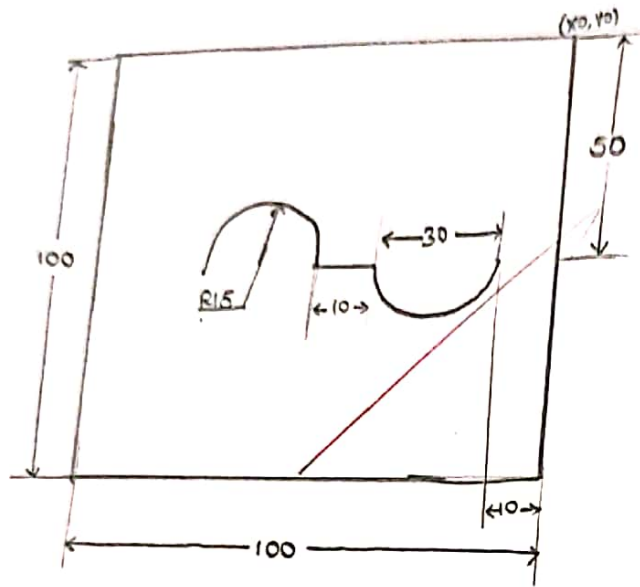
G28 X0 Y0

M05

M30

20
20

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	



Planning & operation sheet

Billet size : 100x100x10				Material : Aluminium			
Program no. : 1002				DWG No : 22			
Sl no.	Operation	Tool type	Tool dia	Tool station	Tool length offset	Spindle speed	Feed mm/min
1	Linear	slot cutter	6mm	1	1	2000	30-50

DATE
EXP. NO. 21

Write a manual part program for circular interpolation for the component shown in figure below.

G21 G94

G91 G28 Z0

G28 X0 Y0

M06 T0101

M03 S1500

G90 G00 X-10 Y-50 Z5

G01 Z-1 F30

G02 X-40 Y-50 R15

G01 X-50 Y-50

G03 X-80 Y-50 R15

G00 Z5

G91 G28 Z0

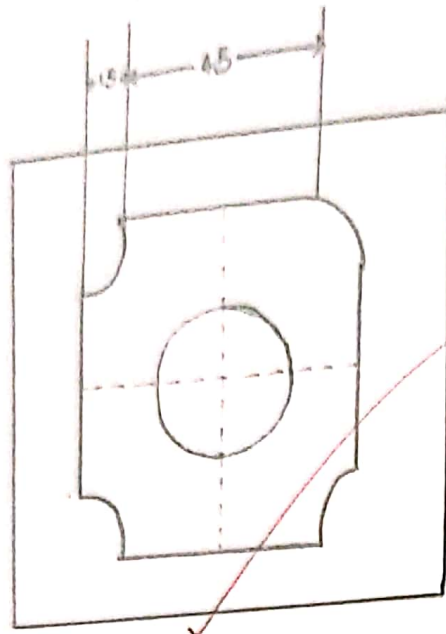
G28 X0 Y0

M05

M30

20
20

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	<i>[Signature]</i>



Planning & operations sheet

Billet size: 100x100x10				Material: Aluminium			
Program no. : 1023				DWG No: 23			
Sl. no.	Operation	Tool type	Tool dia	Tool station	Tool length offset	Spindle speed	Feed mm/min
1	Contouring	Slot cutter	6mm	1	1	2000	30-50

Write a manual part program for contouring operation for the component shown in figure below

G21 G94

G91 G28 Z0

G28 X0 Y0

M06 T1

M03 S2000

G90 G00 X0 Y-37.5 Z5

G01 Z-1 F50

G01 X-22.5 Y-37.5

G03 X-37.5 Y-22.5 R15

G01 X-37.5 Y22.5

G01 X-37.5 Y22.5

G03 X-22.5 Y37.5 R15

G01 X22.5 Y37.5

G02 X37.5 Y22.5 R15

G01 X37.5 Y-22.5

G03 X22.5 Y-37.5 R15

G01 X0 Y-37.5

G00 Z5

G00 X-15 Y0

G01 Z-1 F50

G02 X15 Y0 R15

G02 X-15 Y0 R15

G91 G28 Z0

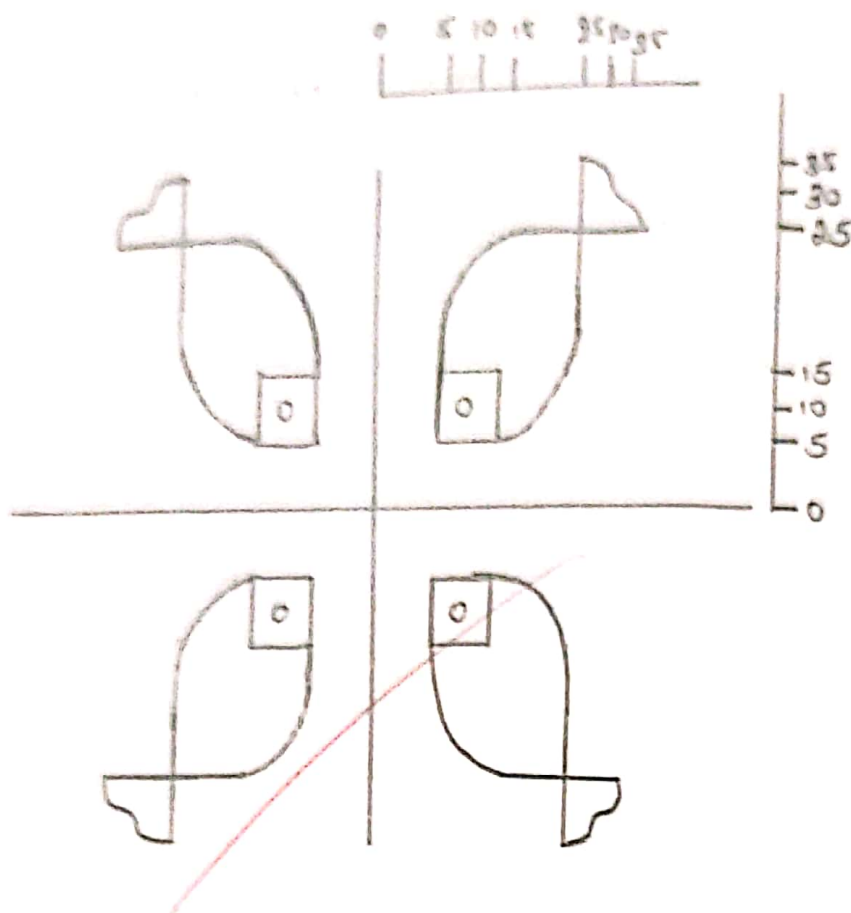
G28 X0 Y0

MD5

MD30

MD5
MD30
MD

	Marks Allotted
Record	20
Observation	5
Viva	5
Total	30
Signature of Faculty with date	MD



Planning & operations sheet:

Billet size: 100x100x10				Material: Aluminium			
Program no.: 1008				DWG No: 24			
Sl. no.	Operation	Tool type	Tool dia	Tool station	Tool length offset	Spindle speed	Feed mm/min
1	Contouring	Slot cutter	6mm	1	1	2000	35-50

Write a manual post program for minimising operation for the component shown in figure.

G21 G94

G91 G28 Z0

G28 X0 Y0

M06 T1

M03 S2000

G90 G00 X0 Y0 Z5

G00 Z0

M98 P0015000

M70

M98 P0015000

M80

M98 P0015000

M70

M71

M98 P0015000

M80

M81

M71

M98 P0015000

G00 Z5

G91 G28 Z0

G28 X0 Y0

M05

M30

0.5000

G00 X5 Y5 Z5

G01 2-1 F50

X15 Y5

X15 Y15

X5 Y15

X5 Y5

G00 Z5

X10 Y10

G10 2-1 F50

G00 Z5

X15 Y5

G01 2-1 F50

G03 X25 Y15 R15

G01 X25 Y35

G02 X30 Y30 R5

G02 X35 Y25 R5

G01 X15 Y25

G03 X5 Y15 R15

G00 Z5

G00 X0 Y0

M99

Mudh

	Marks Allotted
Record	19
Observation	5
Viva	5
Total	29
Signature of Faculty with date	<i>and</i>